

eigenvalue

$$\mathcal{L} = A = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \cdot 1 + 2 \cdot 1 \\ 0 \cdot 1 + 3 \cdot 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$Y = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0.1 + 2.1 \\ 1.1 - 1.1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

Let \underline{A} be a square matrix, then if there exists a neeter \underline{x} and a number λ such that $\underline{A}\underline{x} = \lambda \underline{x}$ then λ is called eigenvalue and \underline{x} is called eigenvalue.

Identity mostrix:

homogeneous linear system of equations

This system has always the trivial **0** solution. However, we are interested in the case of non trivial solutions. This holds when

$$\det \left(\underline{A} - \lambda \underline{I} \right) = 0$$

$$\det \left(\frac{1}{4} - \lambda \frac{1}{4} \right) = 0$$

$$\begin{vmatrix} 1 - \lambda & 2 \\ 2 & 4 - \lambda \end{vmatrix} = 0$$

$$(1 - \lambda)(4 - \lambda) - 4 = 0$$

$$(\lambda - 1)(\lambda - 4) - 4 = 0$$

$$\lambda^2 - 5\lambda + 4 - 4 = 0$$

$$\lambda(\lambda - 5) = 0$$

$$\lambda = 0$$
 $\lambda = 5$

The second of the second o

$$\left(\frac{A}{2} - \lambda \stackrel{\top}{=}\right) \approx = 0$$

$$\left(\frac{A}{2} - 5 \stackrel{\top}{=}\right) \approx = 0$$

$$\begin{bmatrix} 1-5 & 2 \\ 2 & 4-5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} e \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -4 & 2 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -4 \times_1 + 2 \times_2 \\ 2 \times_1 - \times_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{cases} -4z_1 + 2z_2 = 0 \\ 2z_1 - z_2 = 0 \end{cases}$$

$$\begin{cases} 2x_1 - x_2 = 0 \\ \frac{2x_1 - x_2}{2} = 0 \end{cases}$$

$$x_2 = 2x_1$$

that is

$$x_2 = 2x_1$$

This equation admits infinite solutions. This is not surprising because singe the very beginning we have imposed the condition to have non-trivial solutions, i.e., det(A - lambda I) = 0. This means that there are infinite vectors such that if they are multiplied by the matrix A, the result will be a vector that will be five times the original one.

For example,
$$x_1 = 1$$
, then

$$\approx 1 = 1$$
, then

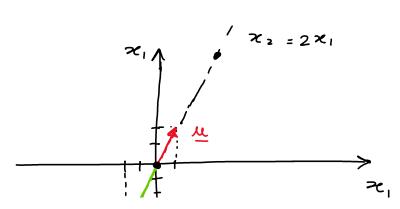
$$\underline{\mathcal{L}} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

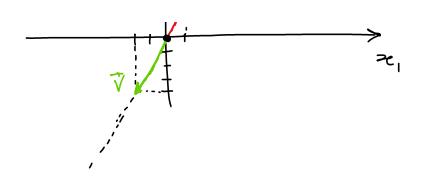
$$\frac{A}{2} = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\frac{A}{2} = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \cdot 1 + 2 \cdot 2 \\ 2 \cdot 1 + 4 \cdot 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 10 \end{bmatrix} = 5 \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 5 \underline{\mu}$$

If
$$x_1 = -2$$
, then $x_2 = -4$

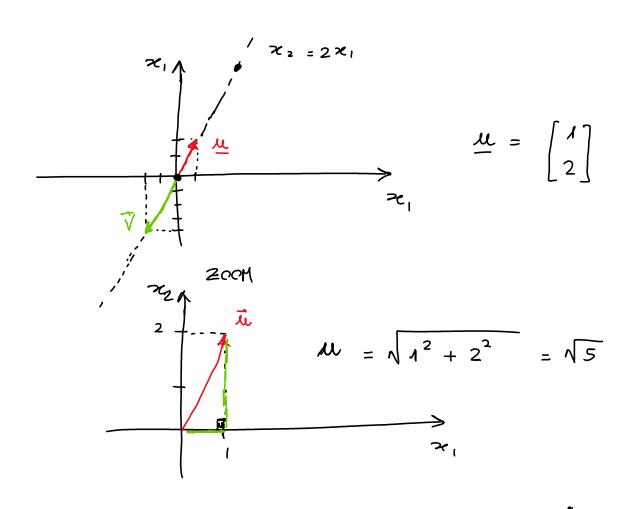
$$Y = \begin{bmatrix} -2 \\ -4 \end{bmatrix}$$





A Verson: is a neeler whose modulus is equal to 1.

If you divide a non-zero vector by its modulus, you get an associated versor (with the same direction and verse).



In general, if you have a rector $\Xi = (\chi_1, \chi_2, \dots, \chi_n), \text{ its modulus is :}$

$$\mathcal{Z} = \left(\mathcal{X}_{1}, \mathcal{X}_{2}, \dots, \mathcal{X}_{m} \right), \text{ its modulus is :}$$

$$\mathcal{Z} = \left(\mathcal{X}_{1}, \mathcal{X}_{2}, \dots, \mathcal{X}_{m} \right), \text{ its modulus is :}$$

This quantity is also defined as the norm of nector ze and can also be denoted as 1|z|, |z|, |z|, |z| an |z|

So, given a vector $\frac{2}{2}$, its associated versor is $\frac{2}{\|2\|}$

$$\frac{d}{dt} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\frac{d}{dt} = \frac{d}{dt} = \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{bmatrix}$$
monnolized
eigenvector

% Compute eigenvalues and eigenvectors
[V, L] = eig(A)

Deagonalizaton:

$$\underline{\underline{A}} = \underline{V} = \underline{V}$$

3) It can be proved that **if A is symmetric** then it admits only real eigenvalues.

That is also why it is better to express a quadratic form with a symmetric matrix A.

TH. on CLASSIFICATION OF QUADRATIC FORMS. Consider a quadratic form Q and let A be the matrix associated to Q. Let λ_1 , λ_2 , ..., λ_n be the eigenvalues of A. Then Q is

Positive definite iff all the eigenvalues of A are positive,

Negative definite if all the eigenvalues of A are negative,

Positive semidefinite if all the eigenvalues of A are not negative and at least one is zero

Negative semidefinite if all the eigenvalues of A are not positive and at least one is zero

Indefinite if A admits both positive and negative eigenvalues

$$Q_1 = 2x_1^2 - 5x_2^2 + 3x_3^2$$
, =

$$= \begin{bmatrix} \varkappa_1 & \varkappa_2 & \varkappa_3 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & -5 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} \varkappa_1 \\ \varkappa_2 \\ \varkappa_3 \end{bmatrix}$$

$$Q4 = 4x_1x_2 - x_1x_3 - 6x_2x_3 =$$

$$= 2 x_{1} x_{2} + 2 x_{2} x_{1} - \frac{1}{2} x_{1} x_{3} - \frac{1}{2} x_{3} x_{1}$$

$$- 3 x_{2} x_{3} - 3 x_{3} x_{2} =$$

$$\begin{bmatrix} x_1^{3}x_2x_3 \end{bmatrix} \begin{bmatrix} 0 & 2 & -\frac{1}{2} \\ 2 & 0 & -3 \\ -\frac{1}{2} & -3 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

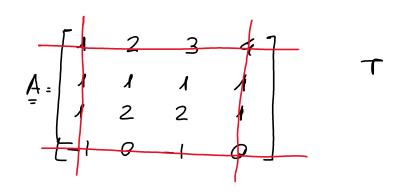
Definition: let $\bf A$ be an n x n matrix. A k x k submatrix of $\bf A$ formed by deleting n - k columns, say columns i_1, i_2, ... i_{n - k} and the same n - k rows from $\bf A$ is called a k-th order principal submatrix of $\bf A$. The determinant of a k x k principal submatrix is called a k - th order principal minor of $\bf A$.

$$i-1$$
 I mean i_1
 $i-\{m-k\}$ i_{m-k}

For example, I horse
$$1 = 2$$

I choose column 1 and 9

I choose column 1 and 4 $i_1 = 1$ $i_2 = 4$



The result is the submartux $\begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}$ This is a 2 nd order principal submatrix of A det $\begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} = 1 \cdot 2 - 2 \cdot 1 = 0$ this is a 2 nd order principal

mina of A.